

# Professional 4-in-1 Cleaning Robot for Small to Medium Spaces

# C40



## Specifications

### Performance

Cleaning Mode	Sweeping Mode, Vacuuming Mode (Sweeping + Vacuuming), Dust Mopping Mode (Sweeping + Dust Mopping)
	Scrubbing Mode (Sweeping + Scrubbing), Water Extraction Mode
Cleaning Efficiency	Up to 1100 m <sup>2</sup> /h
Cleaning Area	Up to 3000 m <sup>2</sup> for Vacuuming and 2500m <sup>2</sup> for Scrubbing
Suction Power	Up to 23500 Pa
Maximum Cleaning Width	Sweeping: 560 mm (With double Side Brushes); Vacuuming and Scrubbing: 400 mm
Dust Collection	8 L Dust Bag, 0.7 L for Separate Dustbin
Clean Water Tank	16 L
Dirty Water Tank	14 L
Battery Life	Sweeping Mode: up to 15 h; Dust Mopping Mode: up to 10 h, Vacuuming Mode: up to 6 h Scrubbing Mode: up to 5 h
Noise	70 dB
Maximum Cleaning Speed	*0.8 m/s (Will be optimized to 1.2 m/s via further upgrades)
Maximum Moving Speed	*0.8 m/s (Will be optimized to 1.2 m/s via further upgrades)
Carpet Cleaning Ability	10 mm
Gap Crossing Ability	35 mm (Navigation);
Obstacle Climbing Ability	15 mm (Navigation, Sweeping + Vacuuming); 5 mm (Sweeping+Scrubbing, not suggested)
Minimum Passable Width	65 cm
Minimum Passable Height	75 cm
Slope Angle	≤ 8° (Navigation only, no cleaning task); ≤ 2° (Cleaning Task)

## Measurements

Robot Dimensions (W × D × H)	616 × 550 × 690 mm
Robot Weight	70 kg (With Battery, Water Tanks are empty, Robot Only)
Charging Pile Dimensions (W × D × H)	534 × 225 × 407 mm
Charging Pile Weight	About 20 kg

## Environment

Operating Temperature and Humidity	0–40°C, 20–80% RH
Operating environment Storage	Indoor environment, carpet (regular low-pile carpet, ≤10 mm), hard floor
Temperature and Humidity	–15–45°C, 20–80% RH

## Battery and Charging

Battery Type	LFP battery
Battery Capacity	DC 25.6 V 50 Ah
Charging Mode	Automatic charging with the charging pile (Additional purchase is required); Manual charging with the bundled recharger
Charging Input	100–240 V~, 50/60 Hz
Charging Time	About 2 h

## Hardware

Machine Material	ABS and aluminum alloy
Positioning Method	Sensor Fusion (LiDAR and VSLAM Sensor)
Positioning Accuracy	Centimeter level
Sensing Techniques	LiDAR, Stereo Vision Sensors, Collision Sensor, IMU (Inertial Measurement Unit), VSLAM Sensor, Line Laser Sensor, Ultrasonic Sensor, RGB Camera
Sensor Coverage	LiDAR detection range: 240°(TBD), <=25 m; Stereo Vision Sensor horizontal coverage: 170°
Network	Wi-Fi; ESP01; 4G
Operation Screen	11.6 inch (1920 × 1080)
Interactive Ability	Light/Touch/Voice Prompts

## System and Function

System	Linux (Control) & Android (Interact)
App Language	Chinese, English, Japanese, Korean, French, Thai, German
App Functions	Immediate Cleaning / Scheduled Cleaning / Manual Cleaning / Teaching Mode